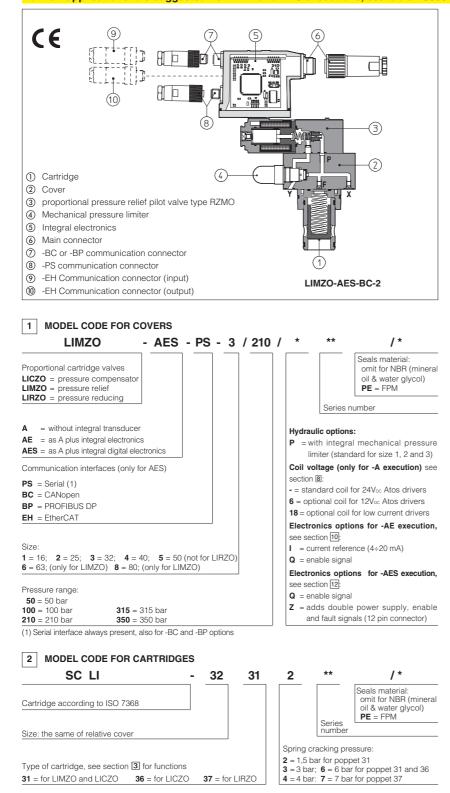


# Proportional pressure control cartridges type LI\*ZO-AES

compensator, relief, reducing, without integral pressure transducer, ISO 7368 sizes from 16 to 80

AES execution included in this table is available only for running supplies or spare parts For new applications it is suggested new AEB and AES executions, see table FS300



#### LICZO, LIMZO and LIRZO are 2-way proportional cartridges without integral pressure transducer which provide respectively pressure compensation, relief and reducing controls according to the electronic referen ce signals.

They operate in association with electro-nic drivers, see table ④ which supply the proportional valve with proper current to align valve regulation to the reference signal supplied to the electronic driver.

These valves are composed by a 2-way cartridge () housed into a standard ISO/DIN cavity and by a closing cover 2 with a piloting proportional pressure relief valve (3) type RZMO, see tab. F007.

They are available in different executions:

• -A, without integral pressure transducer. -AE, -AES, as -A plus analogue (AE) or digital (AES) integral electronics (5).

The integral electronics (5) ensures factory presetting, fine functionality plus valve-tovalve interchangeability and simplified wiring and installation.

The electronic main connector () is fully interchangeable for -AE and -AES executions. Standard 7 pin connector is used for power supply, analog input reference and monitor signals. 12 pin connector is used for option /Z

(AES).

Following communication interfaces ⑦, (8), (9), (10) are available for the digital -AES execution.

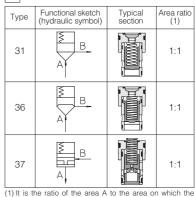
- -PS, Serial communication interface for configuration, monitoring and firmware updating through Atos PC software -
- always present also for -BC -BC, CANopen interface -BP, PROFIBUS-DP interface
- -EH, EtherCAT interface

The valves with -BC and -BP interfaces can be integrated into a fieldbus communication network and thus digitally operated by the machine control unit

The coils are fully plastic encapsulated with insulation class H.

Size: 16, 25, 32, 40, 50, 63, 80, Max flow: up to 3000 l/min. Max pressure: 350 bar

# **3 TYPICAL FUNCTIONS OF CARTRIDGES**



pilot pressure is applied

4 ELECTRONIC DRIVERS FOR LI\*ZO

| Valve model            |   | -A         |             |            |             |             |         |          |  |  |
|------------------------|---|------------|-------------|------------|-------------|-------------|---------|----------|--|--|
| Drivers model          | E-MI-AC-01F   | E-MI-AS-IR | E-BM-AC-01F | E-BM-AS-PS | E-ME-AC-01F | E-RP-AC-01F | E-RI-AE | E-RI-AES |  |  |
| Data sheet             | G010  | G020       | G025        | G030       | G035        | G100        | G110    | G115     |  |  |
| Note: for power supply | Note: for power supply and communication connector see section 15 |            |             |            |             |             |         |          |  |  |

# 5 HYDRAULIC CHARACTERISTICS (based on mineral oil ISO VG 46 at 50 °C)

| Hydraulic syml   | bols                   |                        |                    |   |        |          |       |                    |                        |  |      |      |      |                    |                        |     |     |     |
|--|------------------------|------------------------|--------------------|---|--------|----------|-------|--------------------|------------------------|--|------|------|------|--------------------|------------------------|-----|-----|-----|
|  |                        |                        |                    | PDX $\rightarrow$ |        |          |       |                    | AES)                   | B<br>C<br>C<br>C<br>C<br>C<br>C<br>C<br>C<br>C<br>C<br>C<br>C<br>C |      |      |      |                    |                        |     |     |     |
| Valve model  |                        |                        | LICZO-A, -AE, -AES |   |        |          |       | LIMZO-A, -AE, -AES |                        |  |      |      |      | LIRZO-A, -AE, -AES |                        |     |     |     |
| Valve size   |                        |                        | 16                 | 25  | 32     | 40       | 50    | 16                 | 25                     | 32   | 40   | 50   | 63   | 80                 | 16                     | 25  | 32  | 40  |
| Max flow   |                        | [l/min]                | 200                | 400   | 750    | 1000     | 2000  | 200                | 400                    | 750  | 1000 | 2000 | 3000 | 4500               | 160                    | 300 | 550 | 800 |
| Min regulated pre  | es. at port A          | [bar]                  | 9                  | 8,5   | 8      | 13       | 15    | 7                  | 7                      | 7  | 10,5 | 12   | 12   | (1)                | 7                      |     |     |     |
| Min regulated pre  | es. at port A for /350 | [bar]                  | 11 10 10 13 16     |   |        | 10       | 10    | 9                  | 12                     | 13   | 13   | 16   | 12   |                    |                        |     |     |     |
| Max regulated pr   | es. at port A          | [bar]                  |                    | 50; 100;  | 210; 3 | 315; 350 | )     |                    | 50; 100; 210; 315; 350 |  |      |      |      |                    | 50; 100; 210; 315; 350 |     |     |     |
| Response time 0-100% step signal [ms]<br>(depending on installation) |                        |                        | 100-400            |   |        |          |       | 100-450            |                        |  |      |      |      | 100-350            |                        |     |     |     |
| Hysteresis   | [% of regulated ma     | f regulated max pres.] |                    |   | ≤2     |          | ≤ 1,5 |                    |                        |  |      | ≤ 2  |      |                    |                        |     |     |     |
| Linearity  | [% of regulated ma     | ax pres.]              |                    | ≤ 3   |        |          | ≤ 3   |                    |                        |  |      |      | ≤ 3  |                    |                        |     |     |     |
| Repeatibility [% of regulated max pres.]                             |                        |                        |                    |   | ≤2     |          |       |                    |                        |  | ≤ 2  |      |      |                    |                        | ≤   | 2   |     |

(1) consult our technical office

Above performance data refer to valves coupled with Atos electronic drivers, see section 2.

# 6 MAIN CHARACTERISTICS

| Assembly position                | Any position   |
|----------------------------------|--|
| Subplate surface finishing       | Roughness index Ra 0,4 - flatness ratio 0,01/100 (ISO 1101)  |
| Ambient temperature              | -20°C ÷ +70°C for -A execution; -20°C ÷ +60°C for -AE and -AES;  |
| Fluid                            | Hydraulic oil as per DIN 51524 535 for other fluids see section 1  |
| Recommended viscosity            | 15 ÷100 mm²/s at 40°C (ISO VG 15÷100)  |
| Fluid contamination class        | ISO 4406 class 20/18/15 NAS 1638 class 9, in line filters of 10 µm (β10≥75 recommended)                    |
| Fluid temperature                | -20°C +60°C (standard seals) -20°C +80°C (/PE seals)   |
| Coil resistance R at 20°C        | $3 \div 3.3 \Omega$ for standard; $2 \div 2,2 \Omega$ for option /6; $13 \div 13,4 \Omega$ for option /18  |
| Max solenoid current             | 2,6 A for standard 12 V $_{\rm DC}$ coil; 3,25 A for 6 V $_{\rm DC}$ coil; 1,5 A for 18 V $_{\rm DC}$ coil |
| Max power                        | 30 Watt -A execution; 50 Watt for -AE and AES executions   |
| Protection degree (CEI EN-60529) | IP65 for -A execution; IP67 for -AE and AES executions   |
| Relative duty factor             | Continuous rating (ED=100%)  |

# 7 GENERAL NOTES

LI\*ZO proportional valves are CE marked according to the applicable Directives (e.g. Immunity/Emission EMC Directive and Low Voltage Directive).

Installation, wirings and start-up procedures must be performed according to the general prescriptions shown in table F003 and in the installation notes supplied with relevant components.

The electrical signals of the valve (e.g. monitor signals) must not be directly used to activate safety functions, like to switch-ON/OFF the machine's safety components, as prescribed by the European standards (Safety requirements of fluid technology systems and components-hydraulics, EN-982).

# 8 OPTIONS FOR -A EXECUTION

8.1 Option /6 optional coil to be used with Atos drivers with power supply 12 Vpc8.2 Option /18 optional coil to be used with electronic drivers not supplied by Atos

# 9 CONNECTIONS FOR -A EXECUTION

|     | SOLENOID POWER SUPPLY CONNECTOR |  |  |  |  |  |  |  |  |
|-----|---------------------------------|--|--|--|--|--|--|--|--|
| PIN | Signal description              |  |  |  |  |  |  |  |  |
| 1   | SUPPLY                          |  |  |  |  |  |  |  |  |
| 2   | SUPPLY                          |  |  |  |  |  |  |  |  |
| 3   | GND                             |  |  |  |  |  |  |  |  |

# 10 ANALOG INTEGRAL DRIVERS -AE - OPTIONS

Standard driver execution provides on the 7 pin main connector:

 Power supply
 - 24Vbc must be appropriately stabilized or rectified and filtered; a 2,5 A safety fuse is required in series to the driver power supply.

 Apply at least a 10000 μF/40 V capacitance to single phase rectifiers or a 4700 μF/40 V capacitance to three phase rectifiers

Reference input signal - analog differential input with 0++10 Vbc nominal range (pin D,E), proportional to desired coil current

Monitor output signal - analog output signal proportional to the actual valve's coil current (1V monitor = 1A coil current)

Following options are available to adapt standard execution to special application requirements:

# 10.1 Option /I

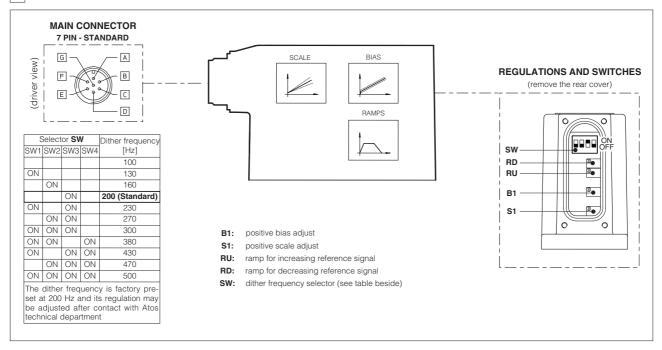
It provides the  $4\div 20$  mA current reference signal instead of the standard  $0\div +10$  Vpc. Monitor output signal is still the standard  $0\div +10$  Vpc It is normally used in case of long distance between the machine control unit and the valve or where the reference signal can be affected by electrical noise; the valve functioning is disabled in case of reference signal cable breakage.

## 10.2 Option /Q

It provides the possibility to enable or disable the valve functioning without cutting the power supply (the valve functioning is disabled but the driver current output stage is still active). To enable the driver supply a 24Vpc on the enable input signal.

## 10.3 Possible combined option: /IQ

#### 11 ANALOG INTEGRAL DRIVERS -AE - MAIN FUNCTIONS AND ELECTRONIC CONNECTIONS



#### 11.1 7 PIN MAIN CONNECTORS

| PIN              | SIGNAL  | TECHNICAL SPECIFICATIONS   | NOTES                  |
|------------------|---------|--|------------------------|
| A                | V+      | Power supply 24 Vbc for solenoid power stage and driver logic                          | Input - power supply   |
| В                | VO      | Power supply 0 Vbc for solenoid power stage and driver logic                           | Gnd - power supply     |
| C <sup>(1)</sup> | AGND    | Ground - signal zero for MONITOR signal  | Gnd - analog signal    |
|                  | ENABLE  | Enable (24 Vbc) or disable (0 Vbc) the driver (for /Q option)                          | Input - on/off signal  |
| D                | INPUT+  | Reference analog differential input: 0÷+10 VDc maximum range (4 ÷ 20 mA for /I option) |                        |
| E                | INPUT - | Normal working range 0÷+10 Vbc (4 ÷ 20 mA for /I option)                               | Input - analog signal  |
| F                | MONITOR | Monitor analog output: 0÷+5 VDc maximum range; 1 V = 1 A                               | Output - analog signal |
| G                | EARTH   | Internally connected to the driver housing   |                        |

Note: (1) with /Q option ENABLE signal replaces AGND on pin C; MONITOR signal is reffered to pin B.

A minimum time of 60ms to 160ms have be considered between the driver energizing with the 24 Vbc power supply and when the valve is ready to operate. During this time the current to the valve coils is switched to zero

#### 12 DIGITAL INTEGRAL DRIVERS -AES - OPTIONS

Standard driver execution provides on the 7 pin main connector:

Power supply - 24Vbc must be appropriately stabilized or rectified and filtered; a 2,5 A safety fuse is required in series to each driver power supply Apply at least a 10000 μF/40 V capacitance to single phase rectifiers or a 4700 μF/40 V capacitance to three phase rectifiers.

Reference input signal - analog differential input with 0÷+10 Vpc nominal range (pin D,E), proportional to desired coil current (4÷20 mA with cable break detection, ± 10 mA, ± 20 mA or 0÷20 mA software selectable

Monitor output signal - analog output signal proportional to the actual valve's coil current (1V monitor = 1A coil current)

Following options are available to adapt standard execution to special application requirements:

#### 12.1 Option /Q

To enable the driver, supply 24Vdc on pin C referred to pin B: when the enable signal is set to zero the valve status is software selectable, by factory default the valve functioning is disabled (zero current to the solenoid) but the driver current output stage is still active. For the complete list of selectable status, see tab. G115.

#### 12.2 Option /Z

It provides, on the 12 pin main connector, the following additional features:

#### Logic power supply

Separated power supply for the solenoid (pin 1, 2) and for the digital electronic circuits (pin 9, 10).

Cutting solenoid power supply allows to interrupt the valve functioning but keeping energized the digital electronics thus avoiding fault conditions of the machine fieldbus controller. This condition allows to realize safety systems in compliance with European Norms EN13849-1 (ex EN954-1).

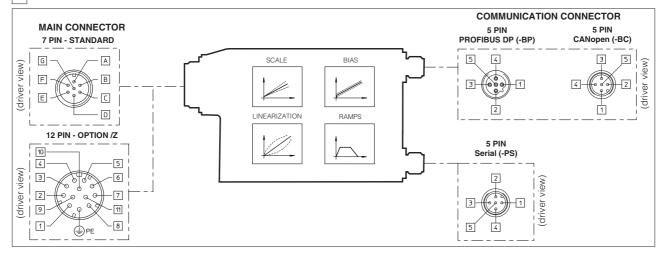
#### **Enable Input Signal**

To enable the driver, supply 24VDC on pin 3 referred to pin 2: when the enable signal is set to zero the valve status is software selectable, by factory default the valve functioning is disabled (zero current to the solenoid) but the driver current output stage is still active. For the complete list of selectable status, see tab. G115.

#### Fault Output Signal

Fault output signal indicates fault conditions of the driver (solenoid short circuits/not connected, reference signal cable broken for 4÷20mA input, etc.). Fault presence corresponds to 0 Vbc, normal working corresponds to 24Vbc (pin 11 referred to pin 2): Fault status is not affected by the Enable input signal.

**13** DIGITAL INTEGRAL DRIVERS - AES - MAIN FUNCTIONS AND ELECTRONIC CONNECTIONS



# 13.1 7 & 12 PIN MAIN CONNECTORS

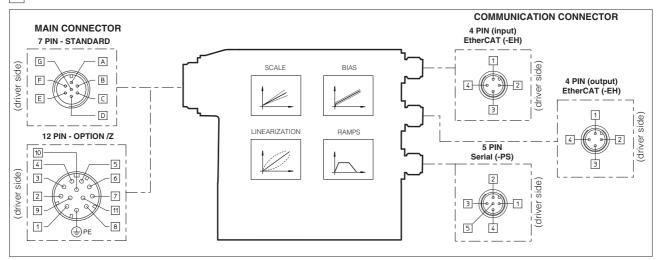
| Standard<br>7pin | /Z option<br>12pin | SIGNAL  | TECHNICAL SPECIFICATIONS  | NOTES                  |
|------------------|--------------------|---------|---|------------------------|
| А                | 1                  | V+      | Power supply 24 Vbc for solenoid power stage (and for driver logic on 7 pin connection)   | Input - power supply   |
| В                | 2                  | VO      | Power supply 0 Vbc for solenoid power stage (and for driver logic on 7 pin connection)  | Gnd - power supply     |
| -                | 3                  | ENABLE  | Enable (24 VDC) or disable (0 VDC) the driver   | Input - on/off signal  |
| D                | 4                  | INPUT+  | Reference analog input: $\pm 10$ Vpc / $\pm 20$ mA maximum range software selectable<br>Default setting 0 $\div$ +10 Vpc differential input | Input - analog signal  |
| E                | -                  | INPUT - | /Z option: common mode INPUT+ referred to AGND  | input unalog orginal   |
| С                | 5                  | AGND    | Ground - signal zero for MONITOR signal<br>signal zero for INPUT+ signal (only for /Z option)   | Gnd - analog signal    |
| F                | 6                  | MONITOR | Monitor analog output: ±5 Vpc maximum range; 1 V = 1 A  | Output - analog signal |
| -                | 7                  | NC      | do not connect  |                        |
| -                | 8                  | NC      | do not connect  |                        |
| -                | 9                  | VL+     | Power supply 24 Vbc for driver logic  | Input - power supply   |
| -                | 10                 | VLO     | Power supply 0 Vbc for driver logic   | Gnd - power supply     |
| -                | 11                 | FAULT   | Fault (0 VDC) or normal working (24 VDC)  | Output - on/off signal |
| G                | PE                 | EARTH   | Internally connected to the driver housing  |                        |

Note: A minimum time of 270 to 340 ms have be considered between the driver energizing with the 24 VDC power supply and when the valve is ready to operate. During this time the current to the valve coils is switched to zero.

# **13.2 ELECTRONIC CONNECTIONS - 5 PIN COMMUNICATION CONNECTORS**

|     |        | -PS Serial                    |          | -BC CANopen             | -BP PROFIBUS DP |                                       |  |  |
|-----|--------|-------------------------------|----------|-------------------------|-----------------|---------------------------------------|--|--|
| PIN | SIGNAL | TECHNICAL SPECIFICATION       | SIGNAL   | TECHNICAL SPECIFICATION | SIGNAL          | . TECHNICAL SPECIFICATION             |  |  |
| 1   | NC     | do not connect                | CAN_SHLD | Shield                  | +5V             | for termination                       |  |  |
| 2   | NC     | do not connect                | NC       | do not connect          | LINE-A          | Bus line (high)                       |  |  |
| 3   | RS_GND | Signal zero data line         | CAN_GND  | Signal zero data line   | DGND            | data line and termination Signal zero |  |  |
| 4   | RS_RX  | Valves receiving data line    | CAN_H    | Bus line (high)         | LINE-B          | Bus line (low)                        |  |  |
| 5   | RS_TX  | Valves transmitting data line | CAN_L    | Bus line (low)          | SHIELD          |                                       |  |  |

# 14 DIGITAL INTEGRAL DRIVER -AES-EH - MAIN FUNCTIONS AND ELECTRONIC CONNECTIONS



Note: for the electronic connections of 7 or 12 pin main connector, see section 13.1

# 14.1 4 & 5 PIN M12 COMMUNICATION CONNECTORS

|     |                                | Serial (-PS)                  |    | EtherCAT (-EH) |        |                                    |  |  |
|-----|--------------------------------|-------------------------------|----|----------------|--------|------------------------------------|--|--|
| PIN | SIGNAL TECHNICAL SPECIFICATION |                               | F  | PIN            | SIGNAL | TECHNICAL SPECIFICATION            |  |  |
| 1   | NC                             | do not connect                |    | 1              | TX+    | Transmitter                        |  |  |
| 2   | NC                             | do not connect                |    | 2              | RX+    | Receiver                           |  |  |
| 3   | RS_GND                         | Signal zero data line         |    | 3              | TX-    | Transmitter                        |  |  |
| 4   | RS_RX                          | Valves receiving data line    |    | 4              | RX-    | Receiver                           |  |  |
| 5   | RS_TX                          | Valves transmitting data line | Ho | using          | Shield | Positioned on control cabinet side |  |  |

# 15 MODEL CODES OF POWER SUPPLY AND COMMUNICATION CONNECTORS (to be ordered separately)

| VALVE VERSION     | -A   | -AE,        | -AES             | -AES/Z | -Serial (-PS)<br>or CANopen (-BC) | PROFIBUS DP<br>(-BP) | EtherCAT (-EH) |  |
|-------------------|------|-------------|------------------|--------|-----------------------------------|----------------------|----------------|--|
| CONNECTOR CODE    | 666  | ZH-7P ZM-7P |                  | ZH-12P | ZH-5P                             | ZH-5P/BP             | ZM-4PM/EH      |  |
| PROTECTION DEGREE | IP65 | IP67        | IP67             | IP67   | IP67                              | IP67                 | IP67           |  |
| DATA SHEET        | K500 |             | G110, G115, K500 | -      | G115, K500                        |                      |                |  |

connectors supplyed with the valve

# 16 PROGRAMMING TOOLS - see tech table GS500

Valve's functional parameters and configurations, can be easily set and optimized using Atos E-SW programming software connected to the digital driver. E-SW software is available in different versions according to the driver's communication interface: PS (Serial) E-SW-PS, BC (CANopen) E-SW-BC and BP (PROFIBUS DP). Proportional valves with fieldbus communication interface can be directly managed by the machine control unit; it is required to implement in the machine control the standard communication as described in the user manuals supplied with the relevant programming software.

# 17 DIAGRAMS OF LICZO/LIMZO (based on mineral oil ISO VG 46 at 50 °C)

#### 17.1 Regulation diagrams

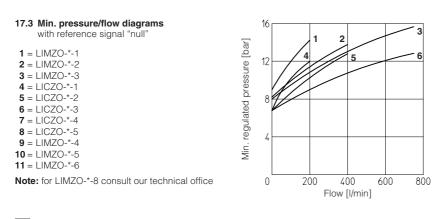
1 = LIMZO-A, LIMZO-AE, LIMZO-AES 2 = LICZO-A, LICZO-AE, LICZO-AES ---- dotted line = /350

#### Note

The presence of counter pressure at port T can affect the effective pressure regulation.

#### 17.2 Pressure/flow diagrams

1 = LICZO-A, LICZO-AE, LICZO-AES LIMZO-A, LIMZO-AE, LIMZO-AES



18 DIAGRAMS OF LIRZO (based on mineral oil ISO VG 46 at 50 °C)

#### 18.1 Regulation diagrams

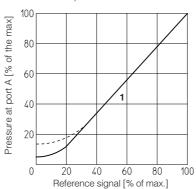
1 = LIRZO-A, LIRZO-AE, LIRZO-AES

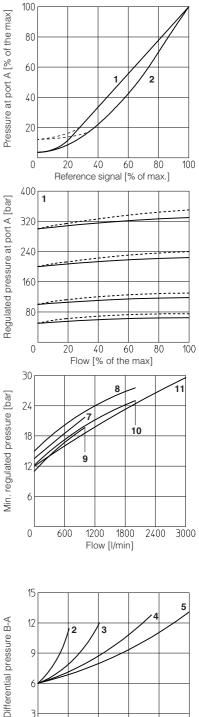
#### 16.2 Min. pressure/flow diagrams with reference signal "null

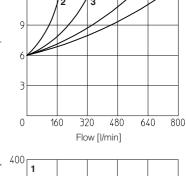
- 2 = LIRZO-\*-1
- **3** = LIRZO-\*-2
- 4 = LIRZO-\*-3
- **5** = LIRZO-\*-4
- ---- dotted line = /350

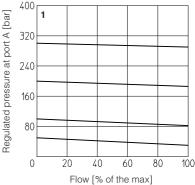
18.3 Pressure/flow diagrams

1 = LIRZO-A, LIRZO-AE, LIRZO-AES









#### 18.4 Dynamic response

The response times in section 3 have to be considered as average values.

The pressure variation in consequence of a modification of the reference input signal to the valve is affected by the stiffness of the hydraulic circuit: greater is the stiffness of the circuit, faster is the dynamic response.

