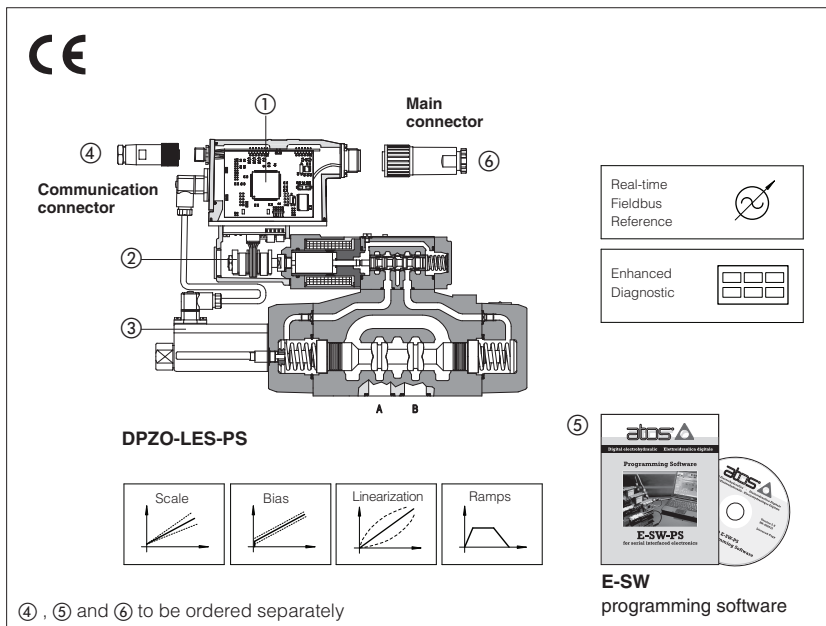


Digital electronic drivers type **E-RI-TES, E-RI-LES**

integral-to-valve format, for proportional valves with one or two spool position transducers

obsolete components - availability on request



These integral digital drivers ① supply and control, in closed loop, the position of the spool or poppet of direct and pilot operated proportional valves according to the electronic reference input signal.

E-RI-TES execution operates direct and pilot operated directional/flow control valves with one integral spool position transducer ②.

E-RI-LES execution operates directional pilot operated valves with two integral spool position transducers ② and ③.

The electronic main connector ④ is fully interchangeable with the same of analog drivers E-RI-TE(LE) (see tab. G200).

Digital communication interface ④ allows to program the drivers with the Atos PC software ⑤. Drivers executions with fieldbus communication interface (CANopen or PROFIBUS DP) are available to program and command the valves directly by the machine control unit.

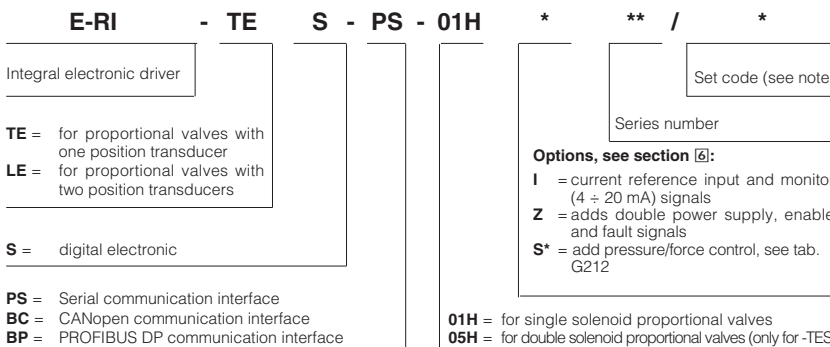
Electrical Features:

- Functional parameters are factory preset for best performances
- Standard 7 pin main connector for power supply, analog input reference and monitor signals
- /Z option 12 pin main connector for additional double power supply, enable and fault signals
- /I option for current reference and monitor signals
- 5 pin connector for communication interface, at choice: serial -PS or fieldbus -BC and -BP
- IP67 protection degree
- CE mark according to EMC directive
- Also available /SP, /SF and /SL options for additional pressure or force control, see tab. G212

Software Features:

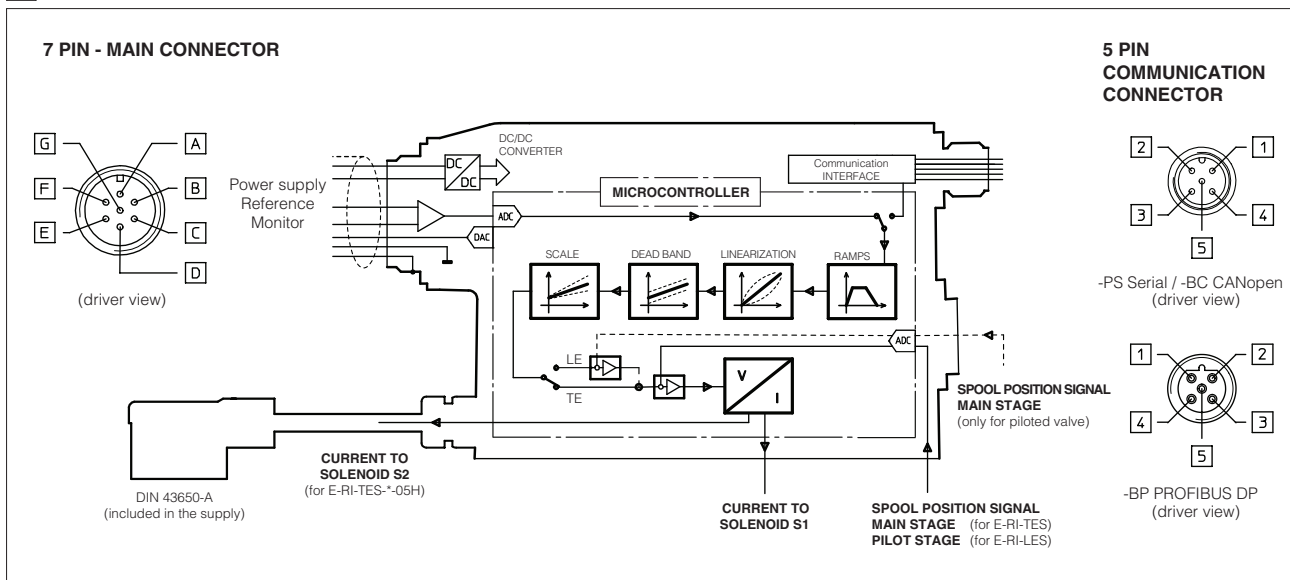
- Setting of valve's functional parameters: bias, scale, ramps, dither
- Linearization function for the hydraulic regulation
- Setting of valve's dynamic response (PID) to optimize the application performances
- Selectable range of electronic reference analog inputs: voltage or current (/I option)
- Complete diagnostics of driver status, solenoid and fault conditions
- Intuitive graphic interface

1 MODEL CODE

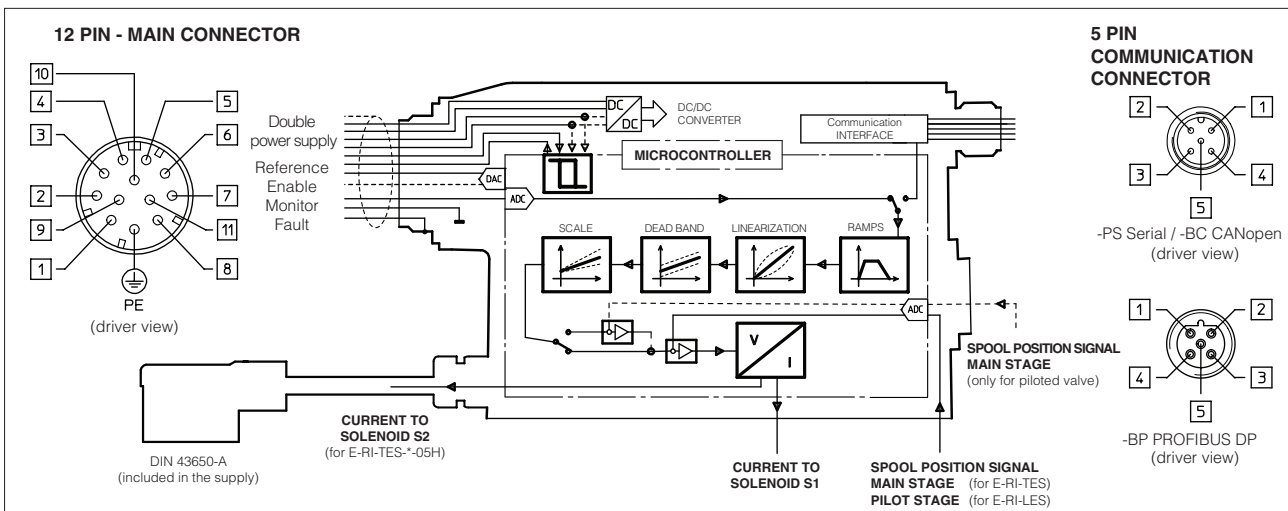


Note: The set code identifies the correspondance between the digital integral driver and the relevant valve; it is assigned by Atos when the driver is ordered as a spare part.

2 BLOCK DIAGRAM



3 BLOCK DIAGRAM - /Z option



4 ELECTRONIC CONNECTIONS - 7 or 12 PIN MAIN CONNECTOR

Standard 7pin	/Z option 12pin	SIGNAL	TECHNICAL SPECIFICATIONS	NOTES
A	1	V+	Power supply 24 Vdc for solenoid power stage (see 6.1)	Input - power supply
B	2	V0	Power supply 0 Vdc for solenoid power stage (see 6.1)	Gnd - power supply
-	3	ENABLE	Enable (24 Vdc) or disable (0 Vdc) the driver (see 6.5)	Input - on/off signal
D	4	INPUT+	Reference analog input: ± 10 Vdc maximum range ($4 \div 20$ mA for /I option) - see 6.2 differential INPUT+ and INPUT - (for 7 pin standard execution) common mode INPUT+ referred to AGND (for 12 pin /Z option)	Input - analog signal
E	-	INPUT -		
C	5	AGND	Ground : signal zero for MONITOR signal (pin F of 7 pin standard or pin 6 of /Z option) signal zero for INPUT+ signal (pin 4 of /Z option)	Gnd - analog signal
F	6	MONITOR	Monitor analog output: ± 10 Vdc maximum range ($4 \div 20$ mA for /I option) - see 6.3	Output - analog signal
-	7	NC	do not connect	
-	8	NC	do not connect	
-	9	VL+	Power supply 24 Vdc for driver digital circuits (see 6.4)	Input - power supply
-	10	VLO	Power supply 0 Vdc for driver digital circuits (see 6.4)	Gnd - power supply
-	11	FAULT	Driver output : Fault (0 Vdc) or normal working (24 Vdc) (see 6.6)	Output - on/off signal
G	PE	EARTH	Internally connected to driver housing	Earth

Note: A minimum time of 270 to 590 ms have be considered between the driver energizing with the 24 Vdc power supply and when the valve is ready to operate. During this time the current to the valve coils is switched to zero.

5 ELECTRONIC CONNECTIONS - 5 PIN COMMUNICATION M12 CONNECTOR

PIN	-PS Serial		-BC CANopen		-BP PROFIBUS DP	
	SIGNAL	TECHNICAL SPECIFICATION	SIGNAL	TECHNICAL SPECIFICATION	SIGNAL	TECHNICAL SPECIFICATION
1	NC	do not connect	CAN_SHLD	Shield	+5V	for termination
2	NC	do not connect	NC	do not connect	LINE-A	Bus line (high)
3	RS_GND	Signal zero data line	CAN_GND	Signal zero data line	DGND	data line and termination Signal zero
4	RS_RX	Valve receiving data line	CAN_H	Bus line (high)	LINE-B	Bus line (low)
5	RS_TX	Valve transmitting data line	CAN_L	Bus line (low)	SHIELD	

6 SIGNALS SPECIFICATIONS

Atos proportional valves are CE marked according to the applicable directives (e.g. Immunity/Emission EMC Directive).

Installation, wirings and start-up procedures must be performed according to the general prescriptions shown in tab. F003 and in the user manuals included in the E-SW programming software.

The electrical signals of the valve (e.g. monitor signals) must not be directly used to activate safety functions, like to switch-ON/OFF the machine's safety components, as prescribed by the European standards (Safety requirements of fluid technology systems and components-hydraulics, EN-982).

6.1 Power supply and wirings (pin A,B / pin 1,2)

The power supply must be appropriately stabilized or rectified and filtered: apply at least a 10000 μ F/40 V capacitance to single phase rectifiers or a 4700 μ F/40 V capacitance to three phase rectifiers.

A safety fuse is required in series to each driver power supply: 2,5 A fuse.

Note: pin 2 and 10 (zero Volt) are connected together inside the electronics.

6.2 Reference Input Signal (pin D,E / pin 4,5)

The driver controls in closed loop the valve spool position proportionally to the external reference signal input.

The driver is designed to receive one analog reference input (pin D,E differential mode input).

The input range and polarity are software selectable within the ± 10 Vdc maximum range; default settings are $0 \div 10$ Vdc for two position single solenoid valves and ± 10 Vdc for double solenoid valves and three position single solenoid valves (see valve's technical table).

Drivers with fieldbus interface (-BC or -BP) can be software set to receive reference value directly by the machine control unit (fieldbus master); in this case the analog reference input signal can be used for start-up and maintenance operations.

Option /I

The maximum range of reference input signal is software selectable among $4 \div 20$ mA (default with cable break detection), ± 10 mA, ± 20 mA or $0 \div 20$ mA

Option /Z

The reference input is available in common mode (pin 4 referred to pin 5) instead of the standard differential mode.

6.3 Monitor Output Signal (pin F,C / pin 6,5)

The driver generates an analog output signal proportional to the actual spool position of the valve (pin F/6 referred to pin C/5); the monitor output signal can be software set to show other signals available in the driver (e.g. analog reference, fieldbus reference, pilot spool position). The output range and polarity are software selectable within ± 10 Vdc maximum range; default settings are $0 \div 10$ Vdc for two position single solenoid valves and ± 10 Vdc for double solenoid valves and three position single solenoid valves (see valve's tech. table).
Option /I: the maximum range of monitor output signal is $4 \div 20$ mA

6.4 Logic power supply (pin 9,10 - only for /Z option)

Option /Z provides separate power supply for the solenoid (pin 1,2) and for the digital electronic circuits (pin 9,10). Cutting solenoid power supply allows to interrupt the valve functioning but keeping energized the digital electronics thus avoiding fault conditions of the machine fieldbus controller. This condition allows to realize safety systems in compliance with European Norms EN13849-1 (ex EN954-1). A safety fuse is required in series to each driver power supply: 500 mA fast fuse.
Note: pin 2 and 10 (zero Volt) are connected together inside the electronics.

6.5 Enable Input Signal (pin 3,2 - only for /Z option)

To enable the driver, supply a 24 Vdc on pin 3 referred to pin 2: Enable input signal allows to enable/disable the current supply to the solenoid, without removing the electrical power supply to the driver; it is used to activate the communication and the other driver functions when the valve must be disabled for safety reasons. This condition does not comply with European Norms EN13849-1 (ex EN954-1).

6.6 Fault Output Signal (pin 11,2 - only for /Z option)

Fault output signal indicates fault conditions of the driver (solenoid short circuits/not connected, reference signal cable broken for $4 \div 20$ mA input, spool position transducer cable broken, etc.). Fault presence corresponds to 0 Vdc, normal working corresponds to 24 Vdc (pin 11 referred to pin2). Fault status is not affected by the Enable input signal.

6.7 Possible combined options: /IZ

7 SOFTWARE TOOLS

The driver configuration and parameters can be easily set with the Atos E-SW programming software, available in three different versions according to the driver's communication interfacing: E-SW-PS (Serial), E-SW-BC (CANopen) and E-SW-BP (PROFIBUS DP).

A proper connection is required between the PC and the electronic driver communication port: for a more detailed description of software interface, PC requirements, adapters, cables and terminators, please refer to tab. GS500.

Proportional valves with fieldbus communication interface (-BC and -BP) can be directly managed by the machine control unit; it is required to implement in the machine control the standard communication as described in the user manuals supplied with the relevant programming software.

Programming software, must be ordered separately :

E-SW-* (mandatory - first supply) = Dvd including E-SW-* software installer and operator manuals; it allows the registration to Atos digital service
E-SW-*N (optional - next supplies) = as above but not allowing the registration to Atos digital service

On first supply of the E-SW-* software, it is required to apply for the registration in the Atos download area : www.download.atos.com .

Once the registration is completed, the password will be sent by email.

The software remains active for 10 days from the installation date and then it stops until the user inputs his password.

With the password you can also download, in your personal area, the latest releases of the Atos software, manuals, drivers and configuration files.

USB Adapters, Cables and Terminators can be ordered separately (see tab. GS500)

8 MAIN SOFTWARE PARAMETER SETTINGS

The following is a brief description of the main settings and features of E-RI-(TE)LES drivers.

For a detailed descriptions of available settings, wirings and installation procedures, please refer to the programming manual E-MAN-RI-LES included in the E-SW-* Dvd programming software (see section [Z]).

8.1 Scale

Scale function allows to set the maximum valve opening at maximum reference signal value.

This regulation allows to reduce the maximum valve regulation in front of maximum reference signal. Two different Scale regulations are available for double solenoid valves or three position single solenoid valves: ScaleA for positive and ScaleB for negative reference signal.

8.2 Bias and Threshold

Proportional valves may be provided with a dead band in the hydraulic regulation corresponding to their switch-off status.

This dead band discontinuity in the valve's regulation can be compensated by activating the Bias function, which adds a fixed preset Bias value to the reference signal (analog or fieldbus external input).

The Bias function is activated when the reference signal overcome the Threshold value, preset into the driver.

The Bias setting allows to calibrate the Bias valve opening to the specific proportional valve to which the driver is coupled.

The Threshold setting is useful to avoid undesired valve regulation at zero reference signal when electric noise is present on the analog input signal: smaller threshold reduces the reference signal dead band, greater values are less affected by electric noise presence.

If fieldbus reference signal is active (see 6.2), threshold should be set to zero.

Two different Bias regulations are available for double solenoid valves: positive reference signals activate BiasA and negative reference signals activate BiasB.

Refer to the programming manuals for a detailed description of other software selectable Bias functions.

8.3 Offset

Proportional valves may be provided with zero overlapping in the hydraulic regulation corresponding to zero reference input signal (valve's central spool position).

The Offset function allows to calibrate the valve's spool central position to the specific hydraulic system setup (e.g. valve applied to cylinder with differential areas). Offset default setting is zero.

8.4 Ramps

The ramp generator allows to convert sudden change of electronic reference signal into smooth time-dependent increasing/decreasing of the valve opening.

Different ramp mode can be set:

- single ramp for any reference variation
- two ramps for increasing and for decreasing reference variations
- four ramps for positive/negative signal values and increasing/decreasing reference variations

Ramp generator is useful for application where smooth hydraulic actuation is necessary to avoid machine vibration and shocks.

If the proportional valve is driven by a closed loop controller, the ramps can lead to unstable behaviour, for these applications ramp function can be software disabled (default setting).

8.5 Linearization

Linearization function allows to set the relation between the reference input signal and the controlled valve's regulation.

Linearization is useful for applications where it is required to linearize the valve's regulation in a defined working condition.

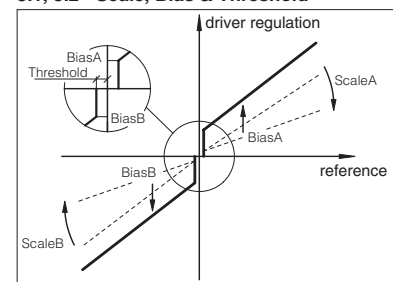
8.6 Dither

The dither is a high frequency modulation added to the valve's reference signal to reduce the hysteresis of the valve's regulation; in fact a small vibration in the valve's hydraulic regulation considerably reduces the mechanical friction effects (e.g. due to cylinder seals).

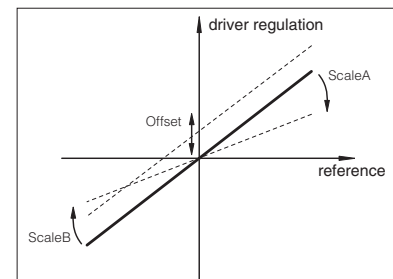
Dither frequency and amplitude are software selectable; the amplitude is automatically reduced at high reference values (high regulated flow / cylinder speed) to avoid possible instability.

Lower frequency and higher amplitude reduce hysteresis but also reduce the regulation stability. In some application this can lead to vibration and noise: right setting usually depends on system setup. Dither default setting is disabled.

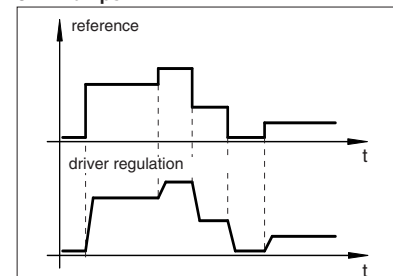
8.1, 8.2 - Scale, Bias & Threshold



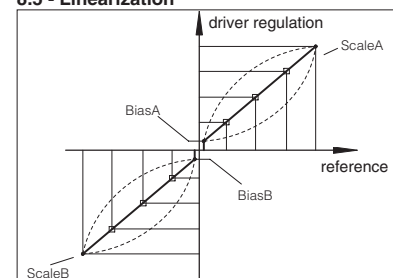
8.3 - Offset



8.4 - Ramps



8.5 - Linearization



9 DRIVER CHARACTERISTICS

Power supply (1) (see 6.1, 6.4)	Nominal : +24 V _{DC} Rectified and filtered : V _{RMS} = 20 ÷ 32 V _{MAX} (ripple max 10 % V _{PP})						
Max power consumption	50 W						
Reference input signal (see 6.2)	Voltage : range ±10 V _{DC} Input impedance: R _i > 50 kΩ Current : range 4 ÷ 20 mA Input impedance: R _i = 316 Ω						
Monitor output (see 6.3)	Output range : voltage ±10 V _{DC} @ max 5 mA current 4 ÷ 20 mA @ max 500 Ω load resistance						
Enable input (see 6.5)	Range : 0 ÷ 5 V _{DC} (OFF state), 9 ÷ 24 V _{DC} (ON state), 5 ÷ 9 V _{DC} (not accepted); Input impedance: R _i > 10 kΩ						
Fault output (2) (see 6.6)	Output range : 0 ÷ 24 V _{DC} (ON state > [power supply - 2 V]; OFF state < 1 V) @ max 50 mA						
Alarms	Solenoid not connected/short circuit, cable break with current reference signal, overtemperature, under temperature, valve spool trasducer cable break						
Format	Sealed box on the valve; IP67 protection degree						
Operating temperature	-20 ÷ 60 °C (storage -20 ÷ 70 °C)						
Mass	approx. 475 g						
Additional characteristics	Short circuit protection of solenoid's current supply; spool position control by P.I.D. with rapid solenoid switching						
Electromagnetic compatibility (EMC)	According to Directive 2004/108/CE (Immunity: EN 50082-2; Emission: EN 50081-2)						
Communication interface Physical Layer Protocol	<table border="1"> <tr> <td>-PS Serial</td> <td>-BC CANopen</td> <td>-BP PROFIBUS</td> </tr> <tr> <td>serial RS232 (not insulated) Atos ASCII coding</td> <td>CAN ISO11898 (optical insulated) CANopen EN50325-4 + DS408</td> <td>RS485 (optical insulated) PROFIBUS DP EN50170-2/IEC61158</td> </tr> </table>	-PS Serial	-BC CANopen	-BP PROFIBUS	serial RS232 (not insulated) Atos ASCII coding	CAN ISO11898 (optical insulated) CANopen EN50325-4 + DS408	RS485 (optical insulated) PROFIBUS DP EN50170-2/IEC61158
-PS Serial	-BC CANopen	-BP PROFIBUS					
serial RS232 (not insulated) Atos ASCII coding	CAN ISO11898 (optical insulated) CANopen EN50325-4 + DS408	RS485 (optical insulated) PROFIBUS DP EN50170-2/IEC61158					
Recommended wiring cable	LiYCY shielded cables: 0,5 mm ² for length up to 40 m [1,5 mm ² for power supply and solenoid]						

Notes: (1) nominal data for solenoid power stage and driver logic; (2) external negative voltage not allowed (e.g. due to inductive loads).

10 MAIN CONNECTOR CHARACTERISTICS (to be ordered separately)

CODE	ZH-7P	ZM-7P	ZH-12P
Type	Female straight circular socket plug 7pin	Female straight circular socket plug 7pin	Female straight circular socket plug 12pin
Standard	According to MIL-C-5015 G	According to MIL-C-5015 G	DIN 43651
Material	Plastic reinforced with fiber glass	Metallic	Plastic reinforced with fiber glass
Cable gland	PG11	PG11	PG16
Cable	LiYCY 7 x 0,75 mm ² max 20 m 7 x 1 mm ² max 40 m	LiYCY 7 x 0,75 mm ² max 20 m 7 x 1 mm ² max 40 m	LiCY 10 x 0,14 mm ² (signal) LiYY 3 x 1 mm ² (power supply)
Connection type	to solder	to solder	to crimp
Protection (EN 60529)	IP 67	IP 67	IP 67

11 COMMUNICATION CONNECTOR CHARACTERISTICS (to be ordered separately)

CODE	-PS Serial Connector	-BC CANopen Connector	-BP PROFIBUS DP Connector
	ZH-5P	ZH-5P	ZH-5P/BP
Type	Female straight circular socket plug 5 pin	Female straight circular socket plug 5 pin	Male straight circular socket plug 5 pin
Standard	M12 – IEC 60947-5-2	M12 – IEC 60947-5-2	M12 – IEC 60947-5-2
Material	Plastic	Plastic	Plastic
Cable gland	PG9	PG9	PG9
Cable	LiYCY 5x0,25 mm ² shielded	CANBus Standard (DR303-1)	PROFIBUS DP Standard
Connection type	screw terminal	screw terminal	screw terminal
Protection (EN 60529)	IP 67	IP 67	IP 67

12 OVERALL DIMENSIONS [mm]

