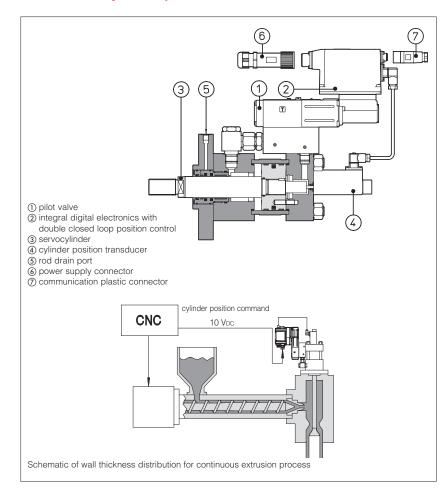


Digital servoactuators for PARISON controls

in blow molding machines

Available only on request



Description:

The Parison control is a well known process used in the plastic blow molding machines for the wall thickness distribution of continuous extruded profiles.

It is mainly used to obtain hollow items, as plastic bottles, tanks, etc, whose thickness can be modulated depending to the required localized mechanical resistance. The wall thickness is realized by means of a spewait intollines is realized by means of a specific servoactuator operated in position closed loop control (see below the application scheme).

The Atos servoactuators CKZ are special proportional servo cylinders with digital integral position control, providing high performances

and high regulation repeatability.
The integral and compact execution ensures the best stiffness of the hydraulic system and it permits high dynamics and position accuracy.

Characteristics:

The digital servoactuator is composed by:

- Special cylinder equipped with low friction seals and with LVDT position transducer. The rod end is threaded for the connection to the extrusion head
- High dynamic proportional valve with zero lapped spool and LVDT position transducer
- · Digital integral electronics with double position closed loop control of pilot valve and of cylinder rod. The -PS serial communication interface permits to optimize the application's performances, modifying via software, the internal parameters by means of the relevant programming device. E.W. of the relevant programming device E-SW-PS to be used with standard PC

The servoactuator is operated by means of analog commands sent to the 7 or 12 pins power supply connector.

The command signal 0÷10 VDC defines the servocylinder rod position in the stroke range 0-12 mm.

The default condition is 0 Vpc = rod position fully in; 10 Vpc = rod position 12 mm.

Available sizes: Ø 63/28, Ø 80/36, Ø 100/45, Ø 125/45, Ø 160/70, Ø 200/90 mm.



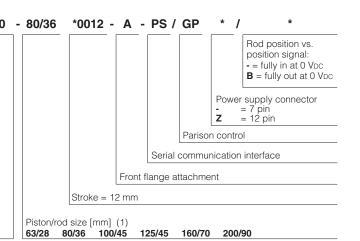
060810 CKZ - X - NN - 1 Mounting flange with threaded holes Servoactuator type: **CKZ** = ISO 6020-2 Control type: X = position/speed Position/speed transducer type: $\mathbf{L} = \text{LVDT}$

No pressure/force control and no pressure/force transducer

Proportional valve size:

- **1** = size 06 (only for cylinder size 63/28, 80/36, 100/45) **2** = size 10 (only for cylinder size 160/70 and 200/90)

Subplate type: **0** = standard



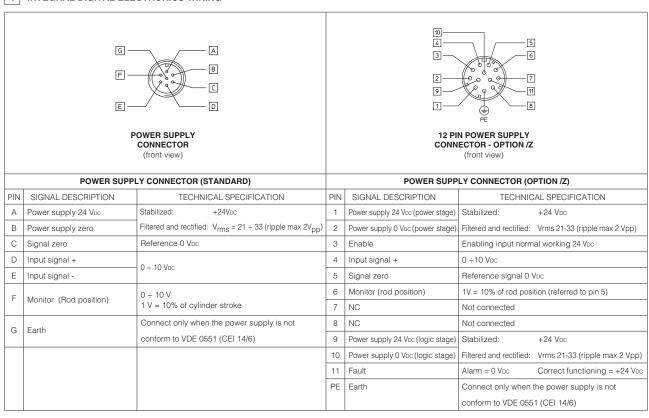
2 SERVOACTUATOR COMPOSITION

Servoactuator model code	Servocylinder code	Servoproportional pilot valve code (see tab. F180)		
060810 CKZ-XL-NN-10-63/28*0012-A-PS/GP	07K0323 CKT/10-9-63/28*0012-A002-L-B1X1			
060810 CKZ-XL-NN-10-80/36*0012-A-PS/GP	02K1260 CKT/10-9-80/36*0012-A002-L-B1X1	050001 DILIZO TEZ INI DO 040 I 51/D		
060810 CKZ-XL-NN-10-100/45*0012-A-PS/GP	06K0120 CKT/10-9-100/45*0012-A002-L-B1X1	050321 DLHZO-TEZ-LN-PS-040-L51/B		
060810 CKZ-XL-NN-10-125/45*0012-A-PS/GP	06K0123 CKT/10-9-125/45*0012-A002-L-B1X1			
060810 CKZ-XL-NN-20-160/70*0012-A-PS/GP	06K0219 CKT/20-9-160/70*0012-A002-L-B1X1	- 060288 DLKZOR-TEZ-LN-PS-140-L31/B		
060810 CKZ-XL-NN-20-200/90*0012-A-PS/GP	08K0125 CKT/20-9-200/90*0012-A002-L-B1X1	000200 DERZON-TEZ-EN-F3-140-L31/B		

3 MAIN CHARACTERISTICS

Bore diameter		[mm]	63	80	100	125	160	200
Rod diameter		[mm]	28	36	45	45	70	90
Working stroke		[mm]	12					
Max pressure		[bar]	160					
Max force	(kN) -	Pull	40	64	100	170	260	400
		Push	50	80	125	190	320	500
Max speed		[m/s]	0,5					
Command signal [VDC]			0÷10 (0V = rod fully in: standard) (0V = rod fully out: option /B)					
Linearity			0,03 %					
Response time at step signal (0-100%) [ms]			85	115	300	320	30	00

4 INTEGRAL DIGITAL ELECTRONICS WIRING



		MMUNICATION CONNECTOR	
	Communication options PS (RS232) male connector		
	1	NC	
	'	Not Connected	2 — 1
	2	NC	
otion		Not Connected	3 4
umbe sscrip	number description \omega_\n	RS_GND	
al de	3	Signal zero data line	5
Pin Signal	4	RS_RX	COMMUNICATION
"		Valves receiving data line	CONNECTOR (front view)
	5	RS_TX	(Hone view)
		Valves transmitting data line	

5 MODEL CODE of power supply and communication connectors (to be ordered separately)

POWER SUPPLY CONNECTOR	COMMUNICATION CONNECTOR		
ZH-7P	<i>7</i> H-5P		
ZH-12P (option /Z)	20-35		

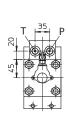
6 PROGRAMMING DEVICES

The functional parameters of the servoactuator, as the bias, scale, ramp and linearization of the regulation characteristic, can be easily set and optimized with graphic interface by using the following software programming devices suitable for standard PC:

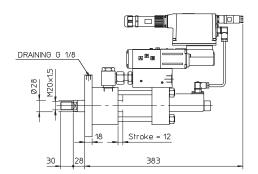
E-SW-PS for electronics with RS232 interface (option -PS) see tab. G500 for complete information about the programming device kits and for the PC minimum requirements.

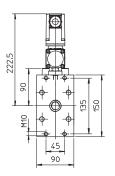
060810 CKZ-XL-NN-10-63/28*0012-A-PS-GP

P, T = 3/8"



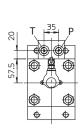
Mass: 18 kg



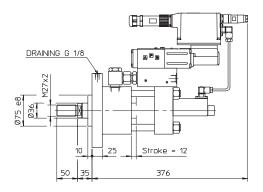


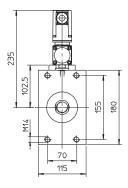
060810 CKZ-XL-NN-10-80/36*0012-A-PS-GP

P, T = 3/8"



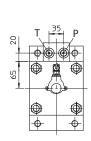
Mass: 26 kg



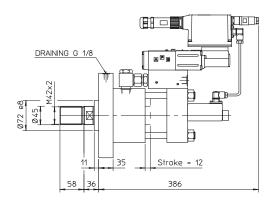


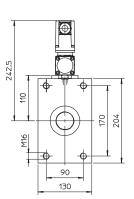
060810 CKZ-XL-NN-10-100/45*0012-A-PS-GP

P, T = 3/8"



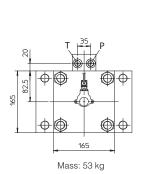
Mass: 36 kg

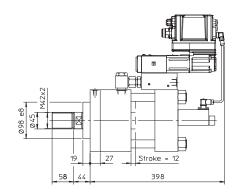


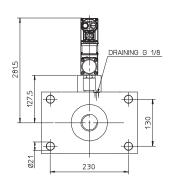


060810 CKZ-XL-NN-10-125/45*0012-A-PS-GP

P, T = 3/8"

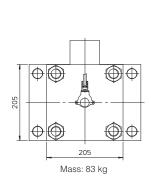


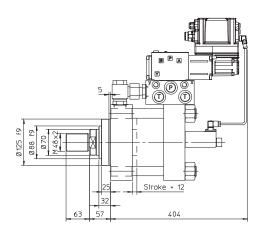


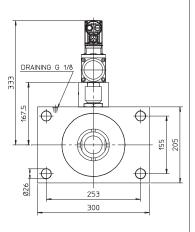


060810 CKZ-XL-NN-20-160/70*0012-A-PS-GP

P, T = 3/4" X, Y = 1/4"







060810 CKZ-XL-NN-20-200/90*0012-A-PS-GP

P, T = 3/4" X, Y = 1/4"

